

# Modeling and Control of a DC-DC Boost Converter for Stable DC Microgrid Integration

**Sudeep Kumar Mohaney**

Assistant Professor

Electrical Engineering Department  
Jabalpur Engineering College, Jabalpur

**Pradeeti Lakra**

Assistant Professor

Electrical Engineering Department  
Jabalpur Engineering College, Jabalpur

**Abstract-** The growing demand for sustainable and efficient energy systems has emphasized the importance of DC microgrids in modern power systems. DC-DC boost converters play a pivotal role in ensuring the stable and efficient operation of DC microgrids by stepping up voltage levels to meet load requirements. This study focuses on the analysis of conventional DC-DC boost converters for their application in DC microgrid systems. Key parameters such as efficiency, voltage gain, input-output characteristics, and dynamic performance are evaluated under varying load and input conditions. The paper also investigates the limitations of conventional boost converters, such as reduced efficiency at high duty cycles, and their impact on microgrid performance. Through simulation and experimental validation, the study provides insights into optimizing converter design and control strategies to enhance reliability and performance in DC microgrid operations. The findings contribute to advancing the integration of renewable energy sources and the development of sustainable energy solutions for future power systems.

**Keywords-** DC-DC Boost Converter, DC Microgrid, Voltage Gain, Converter Efficiency, Renewable Energy Integration, Power System Stability, Load Regulation, Converter Optimization.

## I. INTRODUCTION

The transition toward renewable energy sources and sustainable energy systems has driven the adoption of DC microgrids, which offer several advantages, including reduced energy losses, simplified power management, and seamless integration of renewable energy technologies. Within these systems, the DC-DC boost converter is a critical component, designed to step up the input voltage to meet the operational requirements of various loads and energy storage systems.

Conventional DC-DC boost converters are widely used in DC microgrids due to their simplicity, cost-effectiveness, and ability to achieve significant voltage amplification. However, their performance is highly dependent on parameters such as duty cycle,

switching losses, and input-output voltage variations. At high duty cycles, conventional boost converters often suffer from efficiency degradation and increased electromagnetic interference, which can adversely affect the stability and reliability of the microgrid.

This study aims to analyze the performance of conventional DC-DC boost converters in the context of DC microgrid operation. By examining their efficiency, dynamic response, and limitations, the paper seeks to identify opportunities for improving converter design and operation. Additionally, the work explores strategies to mitigate common challenges, such as reduced efficiency at high duty cycles, thereby enhancing the overall performance of DC microgrids. The insights presented here are expected to facilitate the development of more efficient and reliable energy systems that align with the goals of a sustainable energy future.

## II. CONVERTER AND ROLL IN DC MICROGRID

A DC-DC boost converter is a power electronic device that steps up a lower input DC voltage to a higher output DC voltage. Its role is crucial in DC microgrids, where voltage regulation and energy management are essential to ensure stable and efficient power delivery.

**Working Principle of a Boost Converter**

A conventional boost converter consists of an inductor, a power switch (typically a MOSFET or IGBT), a diode, and a capacitor:

- **Charging Phase (Switch ON):** When the switch is turned on, the inductor stores energy from the input source, causing a voltage drop across it. During this phase, the output load is powered by the charge stored in the capacitor.
- **Discharging Phase (Switch OFF):** When the switch is turned off, the energy stored in the inductor is released through the diode to the load and capacitor, thereby boosting the output voltage.

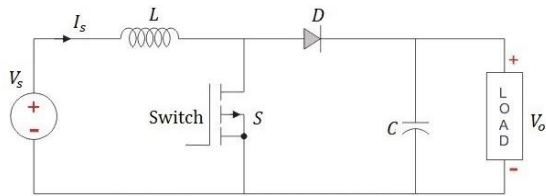


Fig 1: Boost Converter Topology

**Role in DC Microgrid**

In a DC microgrid, the boost converter performs several critical functions:

- **Voltage Level Adjustment:** Renewable energy sources such as solar panels or fuel cells often generate low voltage. A boost converter steps up this voltage to a level compatible with the micro grid’s operating standards.
- **Load Regulation:** By adjusting the duty cycle, the converter ensures that the output voltage remains constant, even under varying load conditions.
- **Integration of Renewable Energy:** The converter smoothens fluctuations caused by intermittent renewable energy sources, such as solar irradiance or wind speed variations.
- **Energy Storage Management:** In systems with batteries or super capacitors, the boost converter facilitates efficient energy transfer between storage devices and the microgrid.

**III. CONVERTER DESIGN AND CONTROL STRATEGIES**

This paper presents the simulation of a DC-DC boost converter using MATLAB/Simulink to evaluate its performance. A 20 V DC source is utilized to power a resistive load, and the boost converter topology consists of a series-connected inductor, MOSFET, and diode. The components in the MATLAB/Simulink model are connected according to the circuit diagram. Figure 2 illustrates the Simulink model of the boost converter topology. In this model, the inductor current is measured using a current sensor, and the load current and load voltage are also monitored. These measurements are then fed into the scope for analysis. The parameter values used in the simulation are listed in the table below.

Table 1: Parameters of Boost Converters

Input Voltage	20 V
Output Voltage	40 V
Inductor	685 μH
Capacitor	100 μF
Resistive Load	40 Ω

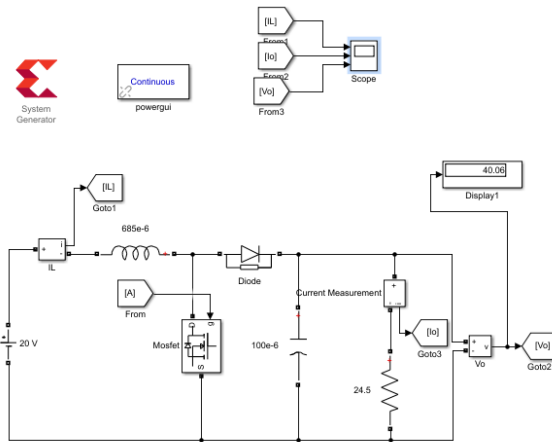


Fig 2: Simulink Model of Boost Converter Topology

To ensure that the boost converter maintains the desired DC link voltage, a **PI (Proportional-Integral)** controller is designed to regulate the output voltage. For proper operation, the converter must function in a closed-loop configuration, where the output is continuously monitored and adjusted to meet the required set point. The PI controller plays a crucial role in tracking and stabilizing the output voltage, ensuring it matches the desired DC link voltage.

To determine the appropriate values for the proportional and integral gains of the controller, the **SISO Tool** in MATLAB is employed. This tool aids in the design and tuning of the controller by providing the necessary system dynamics for achieving optimal performance. The proportional gain (Kp) adjusts the response to the current error, while the integral gain (Ki) eliminates steady-state error by accounting for past errors.

The other parameter of DC-DC Boost converter like inductor and capacitor are designed using the following expression

$$L = \frac{V_{in} * D}{\Delta i_L * f} \tag{1}$$

$$C_{PV} = \frac{D}{R * (\Delta V_o / V_o) * f} \tag{2}$$

Here  $L_{PV}$  is the inductor for PV system,  $V_{in}$  is the input voltage,  $D$  is duty ratio,  $\Delta i_L$  is the ripple in the inductor current,  $f$  is the switching frequency,  $R$  is the load resistance,  $\Delta V_o$  is ripple in output voltage and  $V_o$  is the output voltage.

For the second part where Battery is connected to the DC microgrid using Bidirectional DC-DC converter, in this converter inductor and capacitor is designed using the similar expression show in equation (1) and (2). Fig 3 shows the block diagram for battery system.

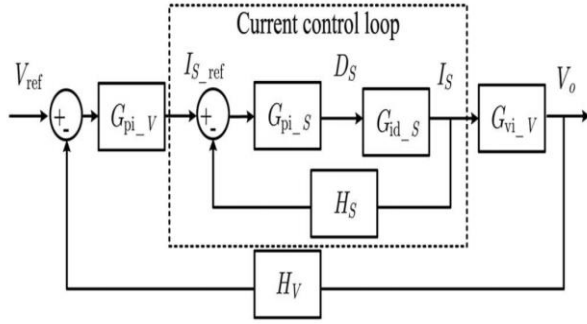


Fig 3: Block diagram for Battery System

Control scheme for battery contains two loops namely current control loop and voltage control loop. In current control loop the transfer function of control to inductor current is given as follows:

$$G_{id} = \frac{\hat{I}_L}{\hat{d}} = \frac{RCSV_o + 2V_o}{RLCS^2 + SL + R(1-D)^2} \quad (3)$$

The transfer function of current control loop compensator is given by

$$G_{pi} = K_p + \frac{K_i}{S} \quad (4)$$

In voltage control loop the transfer function of inductor current to output voltage is given below:

$$G_{vi} = \frac{\hat{V}_o}{\hat{I}_L} = \frac{-SL + R(1-D)^2}{SRC(1-D) + 2(1-D)} \quad (5)$$

The transfer function of voltage control loop compensator is given by

$$G_{pi} = K_p + \frac{K_i}{S} \quad (6)$$

#### IV. EXPERIMENTAL SETUP

The simulation results of the boost converter have been validated through an experimental setup. The experimental setup comprises several key components, each playing a vital role in verifying the performance of the converter.

1. **DC Power Supply:** The primary source of power for the converter is provided by a DC power supply, which delivers the necessary input voltage for the system.
2. **DC-DC Boost Converter:** As shown in Figure 4, the boost converter regulates the input DC voltage to meet the demands of the DC microgrid, adjusting the output voltage as required.
3. **Field Programmable Gate Array (FPGA):** The FPGA serves as the main controller in the system, ensuring the output voltage tracks the desired DC link voltage through precise control of the converter's operation.
4. **Voltage Sensor:** A voltage sensor is used to measure the output voltage at the load. This sensor reduces the

voltage to a level suitable for processing by the microcontroller, enabling accurate feedback for regulation.

5. **Resistive Load:** A resistive load is employed to simulate the DC load connected to the DC link, representing typical load conditions in a microgrid.

The entire experimental setup is designed to replicate the behavior of the conventional boost converter and verify the accuracy and performance of the simulation results under real-world conditions.

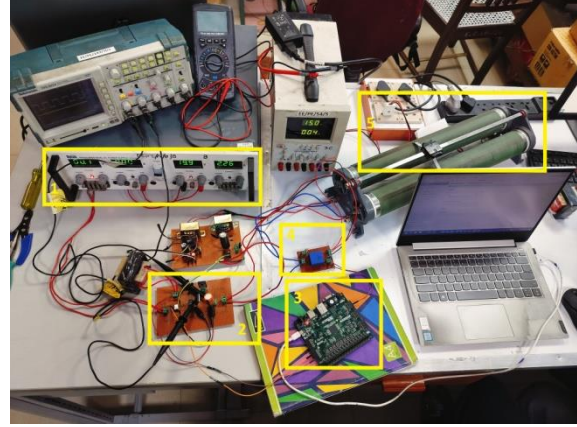


Fig 4: Experimental Setup for Boost Converter Topology

#### V. SIMULATION AND EXPERIMENTAL RESULTS

The simulation study demonstrates that the closed-loop boost converter successfully maintains a constant DC link voltage, even when there are changes in the load or variations in the input voltage. The simulation results are presented in three key waveforms:

1. **Inductor Current:** Represents the current flowing through the inductor during the converter's operation.
2. **Load Current:** Shows the current supplied to the resistive load.
3. **Output Voltage:** Depicts the regulated output voltage delivered to the load.

Figure 5 illustrates these simulation waveforms. Notably, the output voltage waveform exhibits an underdamped characteristic, indicating a slight overshoot before reaching the steady-state value. The settling time of the output voltage is approximately **0.04 seconds**, which suggests that the system stabilizes quickly following any disturbances, such as changes in load or input voltage. This behavior confirms the effectiveness of the closed-loop control in maintaining stable voltage regulation.

The experimental results were obtained using voltage and current probes connected to a Digital Storage Oscilloscope (DSO), which provided real-time measurements of the converter's performance. Figure 6 (to be provided) presents the experimental waveforms for the boost converter topology.

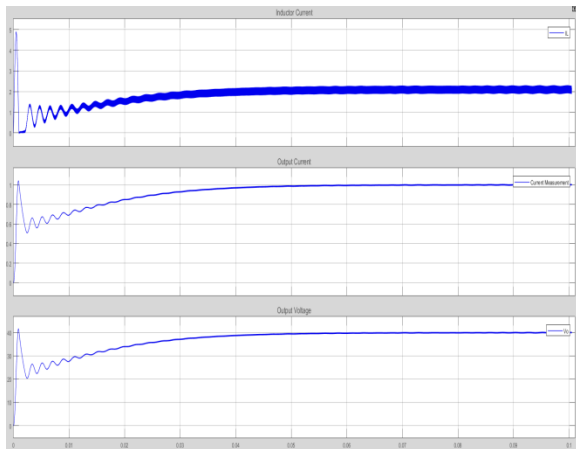


Fig 5: Simulation result of Boost Converter Topology

The first waveform in Figure 6 represents the **drain-to-source voltage (V<sub>ds</sub>)** across the MOSFET, which demonstrates the switching behavior and voltage transitions during operation. The second waveform shows the **output voltage**, which is regulated by the boost converter to maintain a stable output despite changes in input voltage or load conditions.

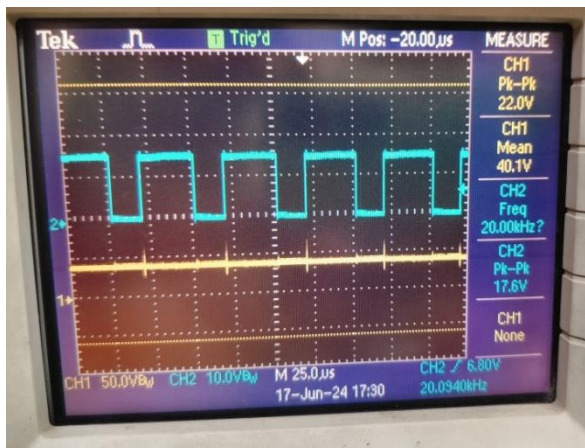


Fig 6: Experimental result of Boost Converter Topology

The mean value of the output voltage in the experiment is measured to be **40 volts**, which confirms that the 20-volt input voltage has been successfully stepped up to 40 volts to maintain the desired constant DC link voltage. This output voltage indicates the boost converter's ability to effectively regulate and stabilize the voltage at a higher level, consistent with the requirements of the DC microgrid.

The settling time of the output voltage is extremely short, so much so that it is not easily visible on the DSO due to the rapid stabilization of the system. This fast settling time further demonstrates the efficiency of the closed-loop control in maintaining voltage regulation.

When comparing the experimental results with the simulation results, both outcomes are consistent,

confirming the accuracy of the simulation model. The experimental data validates the performance of the boost converter and proves that the system operates as expected in real-world conditions, closely matching the simulated behavior.

## VI. CONCLUSION

In this paper, the performance of a DC-DC boost converter in a DC microgrid application has been thoroughly analyzed through both simulation and experimental studies. The simulation results demonstrate that the closed-loop boost converter is capable of maintaining a constant DC link voltage, even under varying load conditions and changes in input voltage. The system exhibits stable operation with a rapid settling time of 0.04 seconds, and the output voltage waveform shows an underdamped characteristic, confirming effective regulation.

The experimental results, obtained using a Digital Storage Oscilloscope (DSO) with voltage and current probes, validate the simulation findings. The output voltage was successfully stepped up from 20 volts to 40 volts, confirming that the converter effectively regulated the DC link voltage as required. The settling time was too short to be clearly observed, which further emphasizes the fast response of the system. Both experimental and simulation results showed excellent agreement, indicating the reliability and accuracy of the boost converter's design and control mechanisms.

Overall, the results highlight the effectiveness of the closed-loop control system in maintaining stable voltage regulation, validating the boost converter's potential for use in DC microgrid applications. This work provides a foundation for further optimization and integration of DC-DC boost converters in renewable energy systems and other voltage-sensitive applications.

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